とうロボ　ロボット紹介用紙

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| 学校名 |  | | | | | | | | |
| チーム名 |  | | | | | | | | |
| ロボット名 |  | | | | | | | | |
| 機体 | 縦 |  | mm | 横 |  | mm | 高さ |  | mm |
| 重さ |  | kg |  | | | | | |
| 製作期間 |  | 月 | ~ |  | 月 |  |  | | |
| 電源 | 種類 |  | | | 数 |  | 個 |  |  |
| 容量 |  | | mAh |  | | | | |
| アクチュエータ | 種類 | | | 型番 | | | 数(個) | | |
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| センサ | 種類 | | | 型番 | | | 数(個) | | |
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| 駆動輪 | 数 |  | 個 | 材質 |  | | Φ |  | mm |
| 入手方法 |  | | | | | | | |
| 補助輪 | 数 |  | 個 |  | | | | | |
| アルミ以外の材質 | 樹脂 |  | | | | | | | |
| 金属 |  | | | | | | | |
| その他 |  | | | | | | | |
| CAD | ソフト  名称 | 機体設計 |  | | | | | | |
| 回路設計 |  | | | | | | |
| マイコン | 種類 | | | 型番 | | | 数(個) | | |
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| プログラム言語 |  | | | | | | | | |
| 走行制御方式 |  | | | | | | | | |